

Descartes' Vier-Kreise-Satz und komplexer Vier-Kreise-Satz

(nach Burnett-Stuart)

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Bemerkung :

Beweise für den Vier-Kreise-Satz und den komplexen Vierkreise-Satz kann man im Internet nur selten finden, und wenn, allenfalls in mehr oder weniger schwieriger Darstellung.

Ziel dieses Skriptums ist es , die Beweise von **Burnett-Stuart** für den Vier-Kreise-Satz und den komplexen Vier-Kreise-Satz ausführlicher und übersichtlicher und damit etwas verständlicher darzustellen.

Quellen :

Burnett-Stuart, George (2014) : A Proof of Descartes' Circle Theorem (concerning four circles, each of which touches the remaining three)

<http://foothills-ts.net/mother/DescartesCircleTheorem.htm>

Burnett-Stuart, George (2014): A Proof of the Extended Descartes' Circle Theorem

<http://foothills-ts.net/mother/ExtendedDescartesCircleTheorem.htm>

Fehringer, Arno (2018) : Der Vier-Kreise-Satz von Descartes (in elementarer Darstellung)

http://mathematikgarten.npage.de/get_file.php?id=33078777&vnr=385360

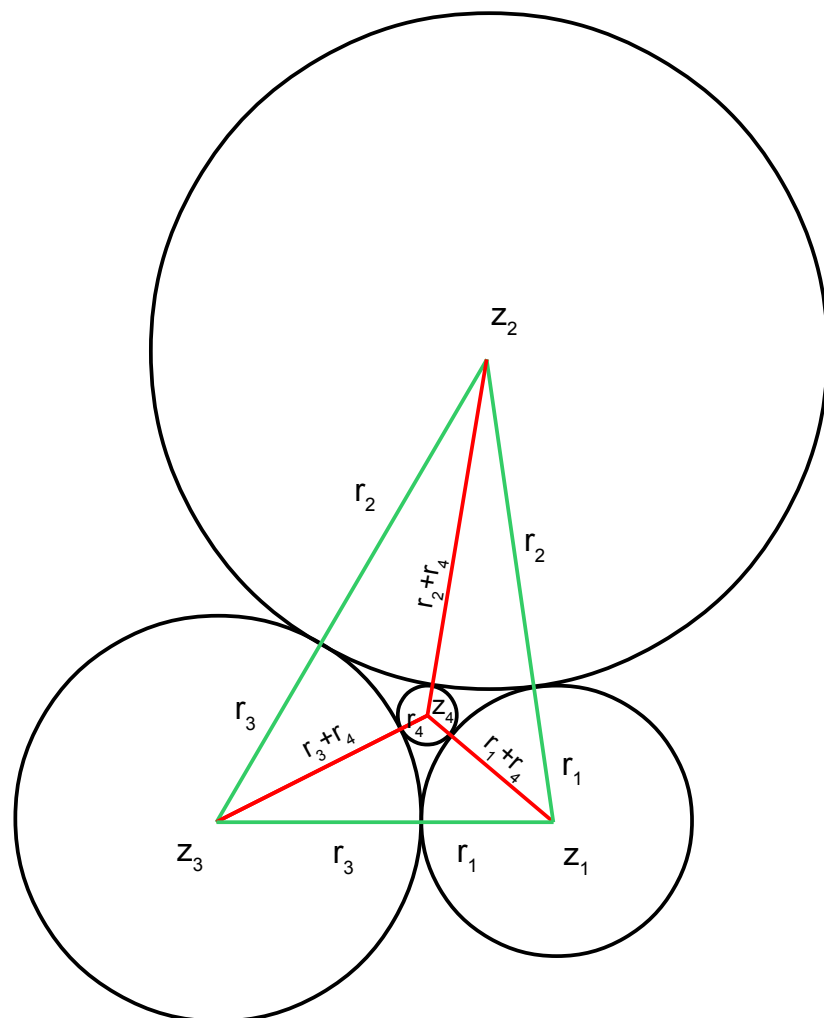
Der Vier-Kreise-Satz von Descartes

Gegeben sind vier paarweise berührende Kreise K_i mit Zentren z_i und Radien r_i , $i \in \{1;2;3;4\}$.

Dann gilt die Gleichung

$$2\left(\frac{1}{r_1^2} + \frac{1}{r_2^2} + \frac{1}{r_3^2} + \frac{1}{r_4^2}\right) = \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4}\right)^2.$$

Beweis :



Winkel :

$$\varphi_{12} := \angle z_1 z_4 z_2, \quad \varphi_{23} := \angle z_2 z_4 z_3, \quad \varphi_{31} := \angle z_3 z_4 z_1$$

Kosinussatz :

$$(r_1+r_2)^2 = (r_1+r_4)^2 + (r_2+r_4)^2 - 2(r_1+r_4)(r_2+r_4)\cos\varphi_{12}$$

$$\cos\varphi_{12} = \frac{(r_1+r_4)^2 + (r_2+r_4)^2 - (r_1+r_2)^2}{2(r_1+r_4)(r_2+r_4)}$$

$$\cos\varphi_{12} = \frac{r_1^2+2r_1r_4+r_4^2 + r_2^2+2r_2r_4+r_4^2 - r_1^2-2r_1r_2-r_2^2}{2(r_1+r_4)(r_2+r_4)}$$

$$\cos\varphi_{12} = \frac{2r_1r_4 + r_4^2 + 2r_2r_4 + r_4^2 - 2r_1r_2}{2(r_1+r_4)(r_2+r_4)}$$

$$\cos\varphi_{12} = \frac{2r_4^2 + 2r_1r_4 + 2r_2r_4 - 2r_1r_2}{2(r_1+r_4)(r_2+r_4)}$$

$$\cos\varphi_{12} = \frac{2r_4^2 + 2r_1r_4 + 2r_2r_4 + 2r_1r_2 - 4r_1r_2}{2(r_1+r_4)(r_2+r_4)}$$

$$\cos\varphi_{12} = \frac{2(r_1+r_4)(r_2+r_4) - 4r_1r_2}{2(r_1+r_4)(r_2+r_4)}$$

$$\cos\varphi_{12} = 1 - 2\frac{r_1r_2}{(r_1+r_4)(r_2+r_4)} \quad (1)$$

Durch zyklische Vertauschung der Indizes erhält man analog :

$$\cos\varphi_{23} = 1 - 2\frac{r_2r_3}{(r_2+r_4)(r_3+r_4)} \quad (2)$$

$$\cos\varphi_{31} = 1 - 2\frac{r_3r_1}{(r_3+r_4)(r_1+r_4)} \quad (3)$$

Additionstheorem für cosinus :

$$\cos\varphi_{12} = \cos\left(\frac{\varphi_{12}}{2} + \frac{\varphi_{12}}{2}\right)$$

$$\cos\varphi_{12} = \cos^2\frac{\varphi_{12}}{2} - \sin^2\frac{\varphi_{12}}{2}$$

$$\cos\varphi_{12} = 1 - \sin^2\frac{\varphi_{12}}{2} - \sin^2\frac{\varphi_{12}}{2}$$

$$\cos\varphi_{12} = 1 - 2\sin^2\frac{\varphi_{12}}{2}$$

$$2\sin^2 \frac{\varphi_{12}}{2} = 1 - \cos \varphi_{12}$$

$$\sin^2 \frac{\varphi_{12}}{2} = \frac{1 - \cos \varphi_{12}}{2}$$

$$\sin \frac{\varphi_{12}}{2} = \sqrt{\frac{1 - \cos \varphi_{12}}{2}}$$

$$\sin \frac{\varphi_{12}}{2} = \sqrt{\frac{1}{2} - \frac{1}{2} \cos \varphi_{12}}$$

$$\sin \frac{\varphi_{12}}{2} = \sqrt{\frac{1}{2} - \frac{1}{2} \left(1 - 2 \frac{r_1 r_2}{(r_1 + r_4)(r_2 + r_4)} \right)} \quad \text{wegen (1)}$$

$$\sin \frac{\varphi_{12}}{2} = \sqrt{\frac{1}{2} - \frac{1}{2} + \frac{r_1 r_2}{(r_1 + r_4)(r_2 + r_4)}}$$

$$\sin \frac{\varphi_{12}}{2} = \sqrt{\frac{r_1 r_2}{(r_1 + r_4)(r_2 + r_4)}}$$

$$\sin^2 \frac{\varphi_{12}}{2} = \frac{r_1 r_2}{(r_1 + r_4)(r_2 + r_4)}$$

Analog erhält man durch zyklische Vertauschung

$$\sin \frac{\varphi_{23}}{2} = \sqrt{\frac{r_2 r_3}{(r_2 + r_4)(r_3 + r_4)}}$$

$$\sin^2 \frac{\varphi_{23}}{2} = \frac{r_2 r_3}{(r_2 + r_4)(r_3 + r_4)}$$

$$\sin \frac{\varphi_{31}}{2} = \sqrt{\frac{r_3 r_1}{(r_3 + r_4)(r_1 + r_4)}}$$

$$\sin^2 \frac{\varphi_{31}}{2} = \frac{r_3 r_1}{(r_3 + r_4)(r_1 + r_4)}$$

Winkelsummensatz :

$$\varphi_{12} + \varphi_{23} + \varphi_{31} = 2\pi$$

$$\frac{\varphi_{12}}{2} + \frac{\varphi_{23}}{2} + \frac{\varphi_{31}}{2} = \pi$$

$$\frac{\varphi_{12}}{2} = \pi - \frac{\varphi_{23}}{2} - \frac{\varphi_{31}}{2}$$

Symmetrie von sinus und Additionstheorem :

$$\sin \frac{\varphi_{12}}{2} = \sin \left(\pi - \frac{\varphi_{23}}{2} - \frac{\varphi_{31}}{2} \right)$$

$$\sin \frac{\varphi_{12}}{2} = \sin \left(\frac{\varphi_{23}}{2} + \frac{\varphi_{31}}{2} \right)$$

$$\sin \frac{\varphi_{12}}{2} = \sin \frac{\varphi_{23}}{2} \cos \frac{\varphi_{31}}{2} + \cos \frac{\varphi_{23}}{2} \sin \frac{\varphi_{31}}{2}$$

Mit $\cos \frac{\varphi_{23}}{2} = \sqrt{1 - \sin^2 \frac{\varphi_{23}}{2}}$, $\cos \frac{\varphi_{31}}{2} = \sqrt{1 - \sin^2 \frac{\varphi_{31}}{2}}$ folgt

$$\sin \frac{\varphi_{12}}{2} = \sin \frac{\varphi_{23}}{2} \sqrt{1 - \sin^2 \frac{\varphi_{31}}{2}} + \sqrt{1 - \sin^2 \frac{\varphi_{23}}{2}} \sin \frac{\varphi_{31}}{2}.$$

Setzt man vorübergehend

$$s := \sin \frac{\varphi_{12}}{2} = \sqrt{\frac{r_1 r_2}{(r_1 + r_4)(r_2 + r_4)}}$$

$$t := \sin \frac{\varphi_{23}}{2} = \sqrt{\frac{r_2 r_3}{(r_2 + r_4)(r_3 + r_4)}}$$

$$u := \sin \frac{\varphi_{31}}{2} = \sqrt{\frac{r_3 r_1}{(r_3 + r_4)(r_1 + r_4)}},$$

so folgt weiter :

$$\sin \frac{\varphi_{12}}{2} = \sin \frac{\varphi_{23}}{2} \sqrt{1 - \sin^2 \frac{\varphi_{31}}{2}} + \sqrt{1 - \sin^2 \frac{\varphi_{23}}{2}} \sin \frac{\varphi_{31}}{2}$$

$$s = t \sqrt{1 - u^2} + \sqrt{1 - t^2} u$$

$$s^2 = t^2(1 - u^2) + 2tu \sqrt{1 - t^2} \sqrt{1 - u^2} + (1 - t^2)u^2$$

$$s^2 = t^2 - t^2 u^2 + 2tu \sqrt{1 - t^2} \sqrt{1 - u^2} + u^2 - t^2 u^2$$

$$s^2 - t^2 - u^2 + 2t^2 u^2 = 2tu \sqrt{1 - t^2} \sqrt{1 - u^2}$$

$$(s^2 - t^2 - u^2 + 2t^2 u^2)^2 = 4t^2 u^2 (1 - t^2)(1 - u^2)$$

$$\begin{aligned} s^4 + t^4 + u^4 + 4t^4 u^4 &= 4t^2 u^2 - 4t^2 u^4 - 4t^4 u^2 + 4t^4 u^4 \\ -2s^2 t^2 - 2s^2 u^2 + 4s^2 t^2 u^2 & \\ +2t^2 u^2 - 4t^4 u^2 & \\ -4t^2 u^4 & \end{aligned}$$

$$s^4 + t^4 + u^4 - 2s^2 t^2 - 2s^2 u^2 + 4s^2 t^2 u^2 + 2t^2 u^2 = 4t^2 u^2$$

$$s^4 + t^4 + u^4 - 2s^2 t^2 - 2s^2 u^2 + 4s^2 t^2 u^2 = 2t^2 u^2$$

$$s^4 + t^4 + u^4 - 2s^2 t^2 - 2s^2 u^2 - 2t^2 u^2 + 4s^2 t^2 u^2 = 0$$

$$\begin{aligned} s^4 + t^4 + u^4 - 2(s^2 t^2 + s^2 u^2 + t^2 u^2) + 4s^2 t^2 u^2 &= 0 \\ 2(s^4 + t^4 + u^4) - (s^4 + t^4 + u^4) - 2(s^2 t^2 + s^2 u^2 + t^2 u^2) + 4s^2 t^2 u^2 &= 0 \end{aligned}$$

$$2(s^4 + t^4 + u^4) - (s^4 + t^4 + u^4 + 2(s^2 t^2 + s^2 u^2 + t^2 u^2)) + 4s^2 t^2 u^2 = 0$$

$$2(s^4 + t^4 + u^4) - (s^2 + t^2 + u^2)^2 + 4s^2 t^2 u^2 = 0$$

$$2\left(\frac{s^2}{t^2u^2} + \frac{t^2}{u^2s^2} + \frac{u^2}{s^2t^2}\right) - \left(\frac{s}{tu} + \frac{t}{us} + \frac{u}{st}\right)^2 + 4 = 0$$

$$2\left(\left(\frac{s}{tu}\right)^2 + \left(\frac{t}{us}\right)^2 + \left(\frac{u}{st}\right)^2\right) - \left(\frac{s}{tu} + \frac{t}{us} + \frac{u}{st}\right)^2 + 4 = 0$$

Zur Rücksubstitution werden zunächst aus den Substitutionsgleichungen

$$s := \sin \frac{\varphi_{12}}{2} = \sqrt{\frac{r_1 r_2}{(r_1 + r_4)(r_2 + r_4)}}$$

$$t := \sin \frac{\varphi_{23}}{2} = \sqrt{\frac{r_2 r_3}{(r_2 + r_4)(r_3 + r_4)}}$$

$$u := \sin \frac{\varphi_{31}}{2} = \sqrt{\frac{r_3 r_1}{(r_3 + r_4)(r_1 + r_4)}}$$

folgende Ausdrücke dargestellt :

$$\frac{s}{tu} = \frac{\sqrt{\frac{r_1 r_2}{(r_1 + r_4)(r_2 + r_4)}}}{\sqrt{\frac{r_2 r_3}{(r_2 + r_4)(r_3 + r_4)}} \sqrt{\frac{r_3 r_1}{(r_3 + r_4)(r_1 + r_4)}}}$$

$$\frac{s}{tu} = \sqrt{\frac{\frac{r_1 r_2}{(r_1 + r_4)(r_2 + r_4)}}{\frac{r_2 r_3}{(r_2 + r_4)(r_3 + r_4)} \frac{r_3 r_1}{(r_3 + r_4)(r_1 + r_4)}}}$$

$$\frac{s}{tu} = \sqrt{\frac{r_1 r_2}{(r_1 + r_4)(r_2 + r_4)} \frac{(r_2 + r_4)(r_3 + r_4)}{r_2 r_3} \frac{(r_3 + r_4)(r_1 + r_4)}{r_3 r_1}}$$

$$\frac{s}{tu} = \sqrt{\frac{(r_3 + r_4)^2}{r_3^2}}$$

$$\frac{s}{tu} = \frac{(r_3 + r_4)}{r_3}$$

$$\frac{s}{tu} = \frac{1}{\frac{r_3}{(r_3 + r_4)}}$$

Analog durch zyklische Vertauschung

$$\frac{t}{us} = \frac{1}{\frac{r_1}{(r_1+r_4)}}$$

$$\frac{u}{st} = \frac{1}{\frac{r_2}{(r_2+r_4)}}$$

Diese Ausdrücke werden nun eingesetzt in

$$2\left(\left(\frac{s}{tu}\right)^2 + \left(\frac{t}{us}\right)^2 + \left(\frac{u}{st}\right)^2\right) - \left(\frac{s}{tu} + \frac{t}{us} + \frac{u}{st}\right)^2 + 4 = 0$$

$$2\left(\left(\frac{1}{\frac{r_1}{(r_1+r_4)}}\right)^2 + \left(\frac{1}{\frac{r_2}{(r_2+r_4)}}\right)^2 + \left(\frac{1}{\frac{r_3}{(r_3+r_4)}}\right)^2\right) - \left(\frac{1}{\frac{r_1}{(r_1+r_4)}} + \frac{1}{\frac{r_2}{(r_2+r_4)}} + \frac{1}{\frac{r_3}{(r_3+r_4)}}\right)^2 + 4 = 0 \quad (4)$$

Die abschließende Umformung ergibt den Satz von Descartes :

Wegen

$$\frac{1}{\frac{r_i}{(r_i+r_4)}} = \frac{r_i+r_4}{r_i} = 1 + \frac{r_4}{r_i}, \quad i \in \{1:2:3\}$$

folgt :

$$2\left(\left(\frac{1}{\frac{r_1}{(r_1+r_4)}}\right)^2 + \left(\frac{1}{\frac{r_2}{(r_2+r_4)}}\right)^2 + \left(\frac{1}{\frac{r_3}{(r_3+r_4)}}\right)^2\right) - \left(\frac{1}{\frac{r_1}{(r_1+r_4)}} + \frac{1}{\frac{r_2}{(r_2+r_4)}} + \frac{1}{\frac{r_3}{(r_3+r_4)}}\right)^2 + 4 = 0$$

$$2\left(\left(1 + \frac{r_4}{r_1}\right)^2 + \left(1 + \frac{r_4}{r_2}\right)^2 + \left(1 + \frac{r_4}{r_3}\right)^2\right) - \left(1 + \frac{r_4}{r_1} + 1 + \frac{r_4}{r_2} + 1 + \frac{r_4}{r_3}\right)^2 + 4 = 0$$

$$2\left(1 + 2\frac{r_4}{r_1} + \left(\frac{r_4}{r_1}\right)^2 + 1 + 2\frac{r_4}{r_2} + \left(\frac{r_4}{r_2}\right)^2 + 1 + 2\frac{r_4}{r_3} + \left(\frac{r_4}{r_3}\right)^2\right) - \left(3 + \frac{r_4}{r_1} + \frac{r_4}{r_2} + \frac{r_4}{r_3}\right)^2 + 4 = 0$$

$$2\left(3 + 2\left(\frac{r_4}{r_1} + \frac{r_4}{r_2} + \frac{r_4}{r_3}\right) + \left(\frac{r_4}{r_1}\right)^2 + \left(\frac{r_4}{r_2}\right)^2 + \left(\frac{r_4}{r_3}\right)^2\right) - \left(3 + \frac{r_4}{r_1} + \frac{r_4}{r_2} + \frac{r_4}{r_3}\right)^2 + 4 = 0$$

Nach vorübergehender Substitution

$$\sigma := \left(\frac{r_4}{r_1} + \frac{r_4}{r_2} + \frac{r_4}{r_3} \right) \quad , \quad \tau := \left(\frac{r_4}{r_1} \right)^2 + \left(\frac{r_4}{r_2} \right)^2 + \left(\frac{r_4}{r_3} \right)^2$$

erhält man

$$2 \left(3 + 2 \left(\frac{r_4}{r_1} + \frac{r_4}{r_2} + \frac{r_4}{r_3} \right) + \left(\frac{r_4}{r_1} \right)^2 + \left(\frac{r_4}{r_2} \right)^2 + \left(\frac{r_4}{r_3} \right)^2 \right) - \left(3 + \frac{r_4}{r_1} + \frac{r_4}{r_2} + \frac{r_4}{r_3} \right)^2 + 4 = 0$$

$$2(3 + 2\sigma + \tau) - (3 + \sigma)^2 + 4 = 0$$

$$6 + 4\sigma + 2\tau - 9 - 6\sigma - \sigma^2 + 4 = 0$$

$$1 - 2\sigma - \sigma^2 + 2\tau = 0$$

$$2\tau + 1 = \sigma^2 + 2\sigma$$

$$2\tau + 2 = \sigma^2 + 2\sigma + 1$$

$$2(\tau + 1) = (\sigma + 1)^2 \quad ,$$

und nach der Resubstitution

$$2 \left(\left(\frac{r_4}{r_1} \right)^2 + \left(\frac{r_4}{r_2} \right)^2 + \left(\frac{r_4}{r_3} \right)^2 + 1 \right) = \left(\frac{r_4}{r_1} + \frac{r_4}{r_2} + \frac{r_4}{r_3} + 1 \right)^2$$

$$2 \left(\frac{r_4^2}{r_1^2} + \frac{r_4^2}{r_2^2} + \frac{r_4^2}{r_3^2} + 1 \right) = \left(\frac{r_4}{r_1} + \frac{r_4}{r_2} + \frac{r_4}{r_3} + 1 \right)^2$$

$$2 \left(\frac{1}{\frac{r_1^2}{r_4^2}} + \frac{1}{\frac{r_2^2}{r_4^2}} + \frac{1}{\frac{r_3^2}{r_4^2}} + \frac{1}{\frac{r_4^2}{r_4^2}} \right) = \left(\frac{1}{\frac{r_1}{r_4}} + \frac{1}{\frac{r_2}{r_4}} + \frac{1}{\frac{r_3}{r_4}} + \frac{1}{\frac{r_4}{r_4}} \right)^2$$

$$2 \left(\frac{1}{\frac{r_1^2}{r_4^2}} + \frac{1}{\frac{r_2^2}{r_4^2}} + \frac{1}{\frac{r_3^2}{r_4^2}} + \frac{1}{\frac{r_4^2}{r_4^2}} \right) = \left(\frac{1}{\frac{r_1}{r_4}} + \frac{1}{\frac{r_2}{r_4}} + \frac{1}{\frac{r_3}{r_4}} + \frac{1}{\frac{r_4}{r_4}} \right)^2$$

(5)

Vier-Kreise-Satz von Descartes (1596 – 1650)

q.e.d.

Der komplexe Vier-Kreise-Satz von Descartes

In der komplexen Zahlenebene $\mathbb{C}$ sind vier paarweise berührende Kreise K_i mit Zentren z_i und Radien r_i , $i \in \{1;2;3;4\}$ gegeben.

Dann gilt die Gleichung

$$2\left(\frac{z_1^2}{r_1^2} + \frac{z_2^2}{r_2^2} + \frac{z_3^2}{r_3^2} + \frac{z_4^2}{r_4^2}\right) = \left(\frac{z_1}{r_1} + \frac{z_2}{r_2} + \frac{z_3}{r_3} + \frac{z_4}{r_4}\right)^2.$$

Beweis :

Wenn die Gleichung richtig ist, dann muss sie für alle Koordinatensysteme richtig sein, speziell muss sie invariant gegenüber Drehungen, Streckungen des Maßstabs und Verschiebungen sein.

Bei Drehungen und Streckungen werden die Koordinaten mit einer Zahl v multipliziert. Auf beiden Seiten der Gleichung kann man deshalb den Faktor v^2 abspalten und weg dividieren, so dass man die ursprüngliche Gleichung erhält, und die Gleichung deshalb auch im neuen Koordinatensystem richtig ist.

$$2\left(\frac{vz_1^2}{r_1^2} + \frac{vz_2^2}{r_2^2} + \frac{vz_3^2}{r_3^2} + \frac{vz_4^2}{r_4^2}\right) = \left(\frac{vz_1}{r_1} + \frac{vz_2}{r_2} + \frac{vz_3}{r_3} + \frac{vz_4}{r_4}\right)^2$$

$$2\left(\frac{z_1^2}{r_1^2} + \frac{z_2^2}{r_2^2} + \frac{z_3^2}{r_3^2} + \frac{z_4^2}{r_4^2}\right)v^2 = \left(\frac{z_1}{r_1} + \frac{z_2}{r_2} + \frac{z_3}{r_3} + \frac{z_4}{r_4}\right)^2 v^2$$

$$2\left(\frac{z_1^2}{r_1^2} + \frac{z_2^2}{r_2^2} + \frac{z_3^2}{r_3^2} + \frac{z_4^2}{r_4^2}\right) = \left(\frac{z_1}{r_1} + \frac{z_2}{r_2} + \frac{z_3}{r_3} + \frac{z_4}{r_4}\right)^2$$

Um die Invarianz gegenüber Verschiebungen w des Koordinatensystems zu garantieren, muss für alle w gelten :

$$2\left(\frac{(z_1-w)^2}{r_1^2} + \frac{(z_2-w)^2}{r_2^2} + \frac{(z_3-w)^2}{r_3^2} + \frac{(z_4-w)^2}{r_4^2}\right) = \left(\frac{z_1-w}{r_1} + \frac{z_2-w}{r_2} + \frac{z_3-w}{r_3} + \frac{z_4-w}{r_4}\right)^2$$

$$2\left(\frac{z_1^2 - 2z_1w + w^2}{r_1^2} + \dots + \frac{z_4^2 - 2z_4w + w^2}{r_4^2}\right) = \left(\frac{z_1-w}{r_1} + \frac{z_2-w}{r_2} + \frac{z_3-w}{r_3} + \frac{z_4-w}{r_4}\right)^2$$

$$2\left(\frac{z_1^2 - 2z_1w + w^2}{r_1^2} + \dots + \frac{z_4^2 - 2z_4w + w^2}{r_4^2}\right) = \left(\frac{z_1}{r_1} + \frac{z_2}{r_2} + \frac{z_3}{r_3} + \frac{z_4}{r_4} - \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4}\right)w\right)^2$$

$$\begin{aligned}
2 \left(\frac{z_1^2}{r_1^2} + \frac{z_2^2}{r_2^2} + \frac{z_3^2}{r_3^2} + \frac{z_4^2}{r_4^2} \right) &= \left(\frac{z_1}{r_1} + \frac{z_2}{r_2} + \frac{z_3}{r_3} + \frac{z_4}{r_4} \right)^2 \\
- 4 \left(\frac{z_1}{r_1} + \frac{z_2}{r_2} + \frac{z_3}{r_3} + \frac{z_4}{r_4} \right) w &- 2 \left(\frac{z_1}{r_1} + \frac{z_2}{r_2} + \frac{z_3}{r_3} + \frac{z_4}{r_4} \right) \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) w \\
+ 2 \left(\frac{1}{r_1^2} + \frac{1}{r_2^2} + \frac{1}{r_3^2} + \frac{1}{r_4^2} \right) w^2 &+ \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right)^2 w^2
\end{aligned}$$

Die Koeffizienten des quadratischen Terms sind nach dem Satz von Descartes (5) gleich.

Der Koeffizientenvergleich des linearen Terms und des Absolutgliedes liefert zwei Gleichungen, deren Gültigkeit nachgewiesen werden muss:

$$2 \left(\frac{z_1}{r_1^2} + \frac{z_2}{r_2^2} + \frac{z_3}{r_3^2} + \frac{z_4}{r_4^2} \right) = \left(\frac{z_1}{r_1} + \frac{z_2}{r_2} + \frac{z_3}{r_3} + \frac{z_4}{r_4} \right) \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) \quad (6)$$

$$2 \left(\frac{z_1^2}{r_1^2} + \frac{z_2^2}{r_2^2} + \frac{z_3^2}{r_3^2} + \frac{z_4^2}{r_4^2} \right) = \left(\frac{z_1}{r_1} + \frac{z_2}{r_2} + \frac{z_3}{r_3} + \frac{z_4}{r_4} \right)^2 \quad (7)$$

Zu Gleichung (6) :

$$2 \left(\frac{z_1}{r_1^2} + \frac{z_2}{r_2^2} + \frac{z_3}{r_3^2} + \frac{z_4}{r_4^2} \right) = \left(\frac{z_1}{r_1} + \frac{z_2}{r_2} + \frac{z_3}{r_3} + \frac{z_4}{r_4} \right) \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right)$$

$$\begin{aligned}
\left[\frac{2}{r_1^2} - \frac{1}{r_1} \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) \right] z_1 &= 0 \\
+ \left[\frac{2}{r_2^2} - \frac{1}{r_2} \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) \right] z_2 & \\
+ \left[\frac{2}{r_3^2} - \frac{1}{r_3} \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) \right] z_3 & \\
+ \left[\frac{2}{r_4^2} - \frac{1}{r_4} \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) \right] z_4 &
\end{aligned}$$

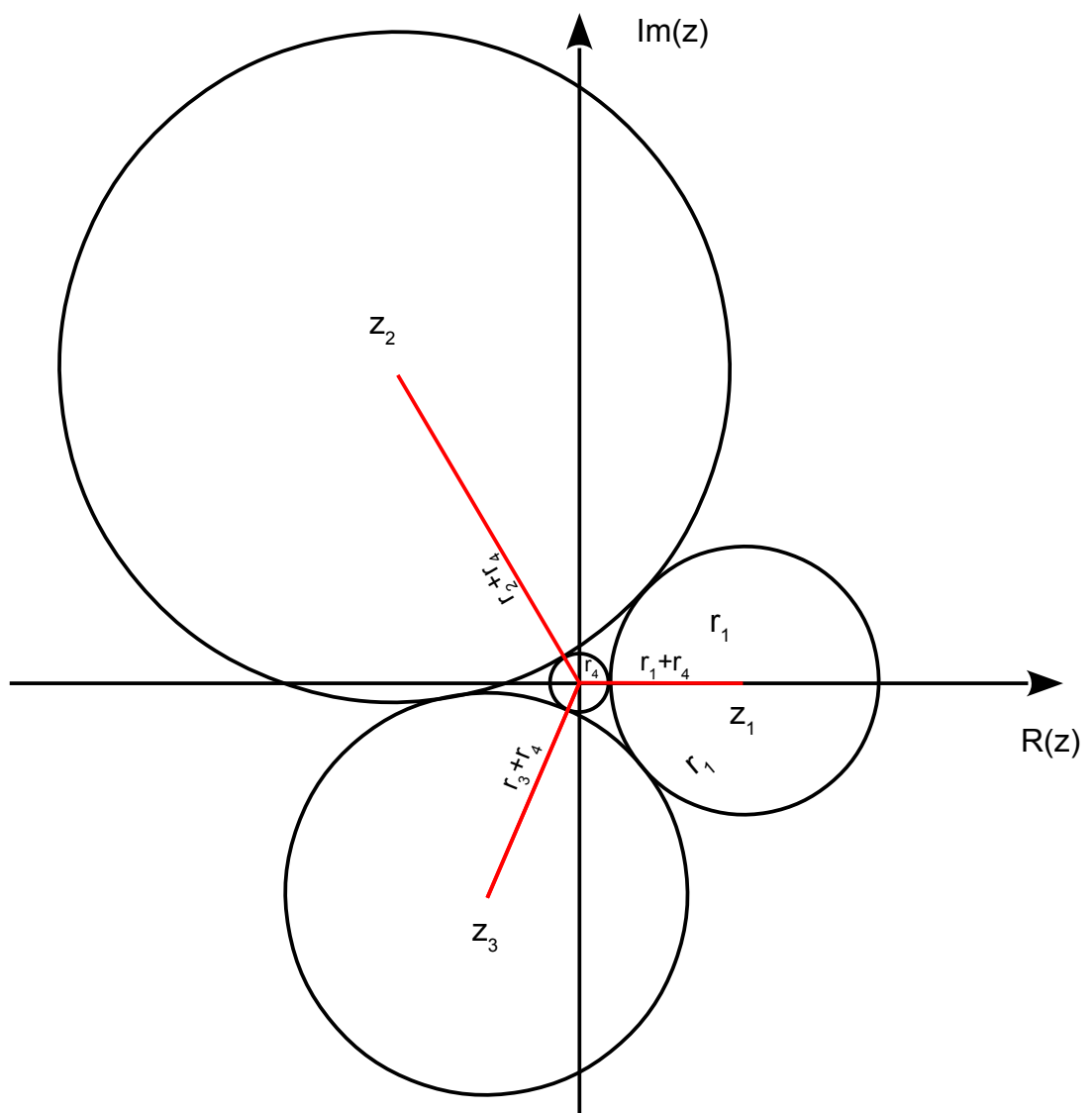
Man zeigt zunächst, dass die Gleichung **(6)** in einem speziellen Koordinatensystem richtig ist.

$$z_1 = r_1 + r_4$$

$$z_2 = (r_2 + r_4) e^{i\varphi_{12}}$$

$$z_3 = (r_3 + r_4) e^{-i\varphi_{31}} \quad \text{mit} \quad \varphi_{12} := \angle z_1 z_2 \quad , \quad \varphi_{31} := \angle z_3 z_4 z_1$$

$$z_4 = 0$$



In diesem speziellen Koordinatensystem lautet Gleichung (6) :

$$\begin{aligned} & \left[\frac{2}{r_1^2} - \frac{1}{r_1} \left(\frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) \right] (r_1 + r_4) = 0 \\ & + \left[\frac{2}{r_2^2} - \frac{1}{r_2} \left(\frac{1}{r_1} + \frac{1}{r_3} + \frac{1}{r_4} \right) \right] (r_2 + r_4) e^{i\varphi_{12}} \\ & + \left[\frac{2}{r_3^2} - \frac{1}{r_3} \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_4} \right) \right] (r_3 + r_4) e^{-i\varphi_{31}} \end{aligned}$$

Umformung ergibt :

$$\begin{aligned} & \left[\frac{2}{r_1^2} - \frac{1}{r_1^2} - \frac{1}{r_1} \left(\frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) \right] (r_1 + r_4) = 0 \\ & + \left[\frac{2}{r_2^2} - \frac{1}{r_2^2} - \frac{1}{r_2} \left(\frac{1}{r_1} + \frac{1}{r_3} + \frac{1}{r_4} \right) \right] (r_2 + r_4) e^{i\varphi_{12}} \\ & + \left[\frac{2}{r_3^2} - \frac{1}{r_3^2} - \frac{1}{r_3} \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_4} \right) \right] (r_3 + r_4) e^{-i\varphi_{31}} \end{aligned}$$

$$\begin{aligned} & \left[\frac{1}{r_1^2} - \frac{1}{r_1} \left(\frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) \right] (r_1 + r_4) = 0 \\ & + \left[\frac{1}{r_2^2} - \frac{1}{r_2} \left(\frac{1}{r_1} + \frac{1}{r_3} + \frac{1}{r_4} \right) \right] (r_2 + r_4) e^{i\varphi_{12}} \\ & + \left[\frac{1}{r_3^2} - \frac{1}{r_3} \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_4} \right) \right] (r_3 + r_4) e^{-i\varphi_{31}} \end{aligned}$$

Jetzt betrachtet man die Terme in den eckigen Klammern :

$$\frac{1}{r_1^2} - \frac{1}{r_1} \left(\frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) = \frac{1}{r_1} \left(\frac{1}{r_1} - \frac{1}{r_2} - \frac{1}{r_3} - \frac{1}{r_4} \right)$$

$$\frac{1}{r_1^2} - \frac{1}{r_1} \left(\frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) = \frac{1}{r_1} \left(\frac{1}{r_1} + \frac{1}{r_4} - \frac{1}{r_2} - \frac{1}{r_4} - \frac{1}{r_3} - \frac{1}{r_4} \right)$$

$$\frac{1}{r_1^2} - \frac{1}{r_1} \left(\frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) = \frac{1}{r_1} \left(\frac{r_1 + r_4}{r_1 r_4} - \frac{r_2 + r_4}{r_2 r_4} - \frac{r_3 + r_4}{r_3 r_4} \right)$$

$$\frac{1}{r_1^2} - \frac{1}{r_1} \left(\frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) = \frac{1}{r_1 r_4} \left(\frac{r_1 + r_4}{r_1} - \frac{r_2 + r_4}{r_2} - \frac{r_3 + r_4}{r_3} \right)$$

$$\frac{1}{r_1^2} - \frac{1}{r_1} \left(\frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) = \frac{1}{r_1 r_4} \left(\frac{1}{\frac{r_1}{r_1 + r_4}} - \frac{1}{\frac{r_2}{r_2 + r_4}} - \frac{1}{\frac{r_3}{r_3 + r_4}} \right)$$

Analog durch zyklische Vertauschung :

$$\frac{1}{r_2^2} - \frac{1}{r_2} \left(\frac{1}{r_1} + \frac{1}{r_3} + \frac{1}{r_4} \right) = \frac{1}{r_2 r_4} \left(\frac{1}{\frac{r_2}{r_2+r_4}} - \frac{1}{\frac{r_3}{r_3+r_4}} - \frac{1}{\frac{r_1}{r_1+r_4}} \right)$$

$$\frac{1}{r_3^2} - \frac{1}{r_3} \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_4} \right) = \frac{1}{r_3 r_4} \left(\frac{1}{\frac{r_3}{r_3+r_4}} - \frac{1}{\frac{r_1}{r_1+r_4}} - \frac{1}{\frac{r_2}{r_2+r_4}} \right)$$

$$\begin{aligned} & \left[\frac{1}{r_1^2} - \frac{1}{r_1} \left(\frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4} \right) \right] (r_1+r_4) = 0 \\ & + \left[\frac{1}{r_2^2} - \frac{1}{r_2} \left(\frac{1}{r_1} + \frac{1}{r_3} + \frac{1}{r_4} \right) \right] (r_2+r_4) e^{i\varphi_{12}} \\ & + \left[\frac{1}{r_3^2} - \frac{1}{r_3} \left(\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_4} \right) \right] (r_3+r_4) e^{-i\varphi_{31}} \end{aligned}$$

$$\begin{aligned} & \frac{1}{r_1 r_4} \left(\frac{1}{\frac{r_1}{r_1+r_4}} - \frac{1}{\frac{r_2}{r_2+r_4}} - \frac{1}{\frac{r_3}{r_3+r_4}} \right) (r_1+r_4) = 0 \\ & + \frac{1}{r_2 r_4} \left(\frac{1}{\frac{r_2}{r_2+r_4}} - \frac{1}{\frac{r_3}{r_3+r_4}} - \frac{1}{\frac{r_1}{r_1+r_4}} \right) (r_2+r_4) e^{i\varphi_{12}} \\ & + \frac{1}{r_3 r_4} \left(\frac{1}{\frac{r_3}{r_3+r_4}} - \frac{1}{\frac{r_1}{r_1+r_4}} - \frac{1}{\frac{r_2}{r_2+r_4}} \right) (r_3+r_4) e^{-i\varphi_{31}} \end{aligned}$$

$$\begin{aligned} & \frac{1}{r_1} \left(\frac{1}{\frac{r_1}{r_1+r_4}} - \frac{1}{\frac{r_2}{r_2+r_4}} - \frac{1}{\frac{r_3}{r_3+r_4}} \right) (r_1+r_4) = 0 \\ & + \frac{1}{r_2} \left(\frac{1}{\frac{r_2}{r_2+r_4}} - \frac{1}{\frac{r_3}{r_3+r_4}} - \frac{1}{\frac{r_1}{r_1+r_4}} \right) (r_2+r_4) e^{i\varphi_{12}} \\ & + \frac{1}{r_3} \left(\frac{1}{\frac{r_3}{r_3+r_4}} - \frac{1}{\frac{r_1}{r_1+r_4}} - \frac{1}{\frac{r_2}{r_2+r_4}} \right) (r_3+r_4) e^{-i\varphi_{31}} \end{aligned}$$

$$\begin{aligned} & \frac{1}{r_1+r_4} \left(\frac{1}{\frac{r_1}{r_1+r_4}} - \frac{1}{\frac{r_2}{r_2+r_4}} - \frac{1}{\frac{r_3}{r_3+r_4}} \right) = 0 \\ & + \frac{1}{r_2+r_4} \left(\frac{1}{\frac{r_2}{r_2+r_4}} - \frac{1}{\frac{r_3}{r_3+r_4}} - \frac{1}{\frac{r_1}{r_1+r_4}} \right) e^{i\varphi_{12}} \\ & + \frac{1}{r_3+r_4} \left(\frac{1}{\frac{r_3}{r_3+r_4}} - \frac{1}{\frac{r_1}{r_1+r_4}} - \frac{1}{\frac{r_2}{r_2+r_4}} \right) e^{-i\varphi_{31}} \end{aligned}$$

Setzt man vorübergehend

$$\alpha := \frac{1}{\frac{r_1}{r_1+r_4}} \quad \beta := \frac{1}{\frac{r_2}{r_2+r_4}} \quad \gamma := \frac{1}{\frac{r_3}{r_3+r_4}}$$

so folgt

$$\underbrace{\frac{1}{\alpha} \left(\frac{1}{\alpha} - \frac{1}{\beta} - \frac{1}{\gamma} \right) + \frac{1}{\beta} \left(\frac{1}{\beta} - \frac{1}{\gamma} - \frac{1}{\alpha} \right) e^{i\varphi_{12}} + \frac{1}{\gamma} \left(\frac{1}{\gamma} - \frac{1}{\alpha} - \frac{1}{\beta} \right) e^{-i\varphi_{31}}}_{=: V} = 0$$

$$V = \frac{1}{\alpha} \left(\frac{1}{\alpha} - \frac{1}{\beta} - \frac{1}{\gamma} \right) + \frac{1}{\beta} \left(\frac{1}{\beta} - \frac{1}{\gamma} - \frac{1}{\alpha} \right) e^{i\varphi_{12}} + \frac{1}{\gamma} \left(\frac{1}{\gamma} - \frac{1}{\alpha} - \frac{1}{\beta} \right) e^{-i\varphi_{31}}$$

Man muss zeigen, dass $V = 0$, also $\operatorname{Re}(V) = 0$ und $\operatorname{Im}(V) = 0$.

$$\operatorname{Re}(V) = \frac{1}{\alpha} \left(\frac{1}{\alpha} - \frac{1}{\beta} - \frac{1}{\gamma} \right) + \frac{1}{\beta} \left(\frac{1}{\beta} - \frac{1}{\gamma} - \frac{1}{\alpha} \right) \cos \varphi_{12} + \frac{1}{\gamma} \left(\frac{1}{\gamma} - \frac{1}{\alpha} - \frac{1}{\beta} \right) \cos \varphi_{31}$$

Nach den Gleichungen (1), (3) gilt

$$\cos \varphi_{12} = 1 - 2 \frac{r_1 r_2}{(r_1 + r_4)(r_2 + r_4)} = 1 - 2\alpha\beta$$

$$\cos \varphi_{31} = 1 - 2 \frac{r_3 r_1}{(r_3 + r_4)(r_1 + r_4)} = 1 - 2\gamma\alpha, \quad ,$$

und es folgt weiter

$$\operatorname{Re}(V) = \frac{1}{\alpha} \left(\frac{1}{\alpha} - \frac{1}{\beta} - \frac{1}{\gamma} \right) + \frac{1}{\beta} \left(\frac{1}{\beta} - \frac{1}{\gamma} - \frac{1}{\alpha} \right) (1 - 2\alpha\beta) + \frac{1}{\gamma} \left(\frac{1}{\gamma} - \frac{1}{\alpha} - \frac{1}{\beta} \right) (1 - 2\gamma\alpha)$$

$$\begin{aligned} \operatorname{Re}(V) &= \frac{1}{\alpha} \left(\frac{1}{\alpha} - \frac{1}{\beta} - \frac{1}{\gamma} \right) \\ &\quad + \frac{1}{\beta} \left(\frac{1}{\beta} - \frac{1}{\gamma} - \frac{1}{\alpha} \right) (1 - 2\alpha\beta) \\ &\quad + \frac{1}{\gamma} \left(\frac{1}{\gamma} - \frac{1}{\alpha} - \frac{1}{\beta} \right) (1 - 2\gamma\alpha) \end{aligned}$$

$$\begin{aligned}\operatorname{Re}(V) &= \frac{1}{\alpha} \left(\frac{1}{\alpha} - \frac{1}{\beta} - \frac{1}{\gamma} \right) \\ &\quad + \frac{1}{\beta} \left(\frac{1}{\beta} - \frac{1}{\gamma} - \frac{1}{\alpha} \right) - 2\alpha \left(\frac{1}{\beta} - \frac{1}{\gamma} - \frac{1}{\alpha} \right) \\ &\quad + \frac{1}{\gamma} \left(\frac{1}{\gamma} - \frac{1}{\alpha} - \frac{1}{\beta} \right) - 2\alpha \left(\frac{1}{\gamma} - \frac{1}{\alpha} - \frac{1}{\beta} \right)\end{aligned}$$

$$\begin{aligned}\operatorname{Re}(V) &= \frac{1}{\alpha^2} - \frac{1}{\alpha\beta} - \frac{1}{\alpha\gamma} \\ &\quad + \frac{1}{\beta^2} - \frac{1}{\beta\gamma} - \frac{1}{\beta\alpha} - 2\frac{\alpha}{\beta} + 2\frac{\alpha}{\gamma} + 2 \\ &\quad + \frac{1}{\gamma^2} - \frac{1}{\gamma\alpha} - \frac{1}{\gamma\beta} - 2\frac{\alpha}{\gamma} + 2 + 2\frac{\alpha}{\beta}\end{aligned}$$

$$\begin{aligned}\operatorname{Re}(V) &= \frac{1}{\alpha^2} - \frac{1}{\alpha\beta} - \frac{1}{\alpha\gamma} \\ &\quad + \frac{1}{\beta^2} - \frac{1}{\beta\gamma} - \frac{1}{\beta\alpha} + 2 \\ &\quad + \frac{1}{\gamma^2} - \frac{1}{\gamma\alpha} - \frac{1}{\gamma\beta} + 2\end{aligned}$$

$$\operatorname{Re}(V) = \frac{1}{\alpha^2} + \frac{1}{\beta^2} + \frac{1}{\gamma^2} - 2 \left(\frac{1}{\alpha\beta} - \frac{1}{\alpha\gamma} - \frac{1}{\beta\gamma} \right) + 4$$

$$\operatorname{Re}(V) = 2 \left(\frac{1}{\alpha^2} + \frac{1}{\beta^2} + \frac{1}{\gamma^2} \right) - \left(\frac{1}{\alpha^2} + \frac{1}{\beta^2} + \frac{1}{\gamma^2} + 2 \left(\frac{1}{\alpha\beta} - \frac{1}{\alpha\gamma} - \frac{1}{\beta\gamma} \right) \right) + 4$$

$$\operatorname{Re}(V) = 2 \left(\frac{1}{\alpha^2} + \frac{1}{\beta^2} + \frac{1}{\gamma^2} \right) - \left(\frac{1}{\alpha} + \frac{1}{\beta} + \frac{1}{\gamma} \right)^2 + 4$$

Die Resubstitution

$$\alpha := \frac{1}{\frac{r_1}{r_1+r_4}} \quad \beta := \frac{1}{\frac{r_2}{r_2+r_4}} \quad \gamma := \frac{1}{\frac{r_3}{r_3+r_4}}$$

ergibt

$$\operatorname{Re}(V) = 2 \left(\frac{1}{\left(\frac{r_1}{r_1+r_4} \right)^2} + \frac{1}{\left(\frac{r_2}{r_2+r_4} \right)^2} + \frac{1}{\left(\frac{r_3}{r_3+r_4} \right)^2} \right) - \left(\frac{1}{\left(\frac{r_1}{r_1+r_4} \right)} + \frac{1}{\left(\frac{r_2}{r_2+r_4} \right)} + \frac{1}{\left(\frac{r_3}{r_3+r_4} \right)} \right)^2 + 4 \quad .$$

Nach Gleichung (4) ist

$$2 \left(\frac{1}{\left(\frac{r_1}{r_1+r_4} \right)^2} + \frac{1}{\left(\frac{r_2}{r_2+r_4} \right)^2} + \frac{1}{\left(\frac{r_3}{r_3+r_4} \right)^2} \right) - \left(\frac{1}{\left(\frac{r_1}{r_1+r_4} \right)} + \frac{1}{\left(\frac{r_2}{r_2+r_4} \right)} + \frac{1}{\left(\frac{r_3}{r_3+r_4} \right)} \right)^2 + 4 = 0 \quad ,$$

also

$$\operatorname{Re}(V) = 0 \quad .$$

Anstatt nun noch zu zeigen, dass $\text{Im}(V) = 0$ ist, kann man auch zeigen, dass der Realteil der Drehung $V e^{-i\varphi_{12}}$ gleich Null ist :

$$\text{Re}(V e^{-i\varphi_{12}}) = 0$$

$$V = \frac{1}{\alpha} \left(\frac{1}{\alpha} - \frac{1}{\beta} - \frac{1}{\gamma} \right) + \frac{1}{\beta} \left(\frac{1}{\beta} - \frac{1}{\gamma} - \frac{1}{\alpha} \right) e^{i\varphi_{12}} + \frac{1}{\gamma} \left(\frac{1}{\gamma} - \frac{1}{\alpha} - \frac{1}{\beta} \right) e^{-i\varphi_{31}}$$

$$V = \frac{1}{\alpha} \left(\frac{1}{\alpha} - \frac{1}{\beta} - \frac{1}{\gamma} \right) + \frac{1}{\beta} \left(\frac{1}{\beta} - \frac{1}{\gamma} - \frac{1}{\alpha} \right) e^{i\varphi_{12}} + \frac{1}{\gamma} \left(\frac{1}{\gamma} - \frac{1}{\alpha} - \frac{1}{\beta} \right) e^{i(\varphi_{12} + \varphi_{23})}$$

$$V e^{-i\varphi_{12}} = \frac{1}{\alpha} \left(\frac{1}{\alpha} - \frac{1}{\beta} - \frac{1}{\gamma} \right) e^{-i\varphi_{12}} + \frac{1}{\beta} \left(\frac{1}{\beta} - \frac{1}{\gamma} - \frac{1}{\alpha} \right) + \frac{1}{\gamma} \left(\frac{1}{\gamma} - \frac{1}{\alpha} - \frac{1}{\beta} \right) e^{i\varphi_{23}}$$

$$V e^{-i\varphi_{12}} = \frac{1}{\beta} \left(\frac{1}{\beta} - \frac{1}{\gamma} - \frac{1}{\alpha} \right) + \frac{1}{\gamma} \left(\frac{1}{\gamma} - \frac{1}{\alpha} - \frac{1}{\beta} \right) e^{i\varphi_{23}} + \frac{1}{\alpha} \left(\frac{1}{\alpha} - \frac{1}{\beta} - \frac{1}{\gamma} \right) e^{-i\varphi_{12}}$$

$$V e^{-i\varphi_{12}} = \frac{1}{\beta} \left(\frac{1}{\beta} - \frac{1}{\gamma} - \frac{1}{\alpha} \right) + \frac{1}{\gamma} \left(\frac{1}{\gamma} - \frac{1}{\alpha} - \frac{1}{\beta} \right) e^{i\varphi_{23}} + \frac{1}{\alpha} \left(\frac{1}{\alpha} - \frac{1}{\beta} - \frac{1}{\gamma} \right) e^{i(\varphi_{23} + \varphi_{31})}$$

Die rechte Seite ist nur eine zyklische Vertauschung von $\text{Re}(V)$.

Man muss nur α , β , γ durch β , γ , α und die Winkel φ_{12} , $-\varphi_{31} = \varphi_{12} + \varphi_{23}$ durch φ_{23} , $-\varphi_{12} = \varphi_{23} + \varphi_{31}$ ersetzen , und eine entsprechende Prozedur liefert

$$\text{Re}(V e^{-i\varphi_{12}}) = 0 \text{ .}$$

Damit ist die Richtigkeit der Gleichung **(6)** gezeigt .

Zu Gleichung (7) :

Man zeigt nun die Gültigkeit der Gleichung

$$2 \left(\frac{z_1^2}{r_1^2} + \frac{z_2^2}{r_2^2} + \frac{z_3^2}{r_3^2} + \frac{z_4^2}{r_4^2} \right) = \left(\frac{z_1}{r_1} + \frac{z_2}{r_2} + \frac{z_3}{r_3} + \frac{z_4}{r_4} \right)^2$$

in dem bereits verwendeten speziellen Koordinatensystem, wobei

$$\begin{aligned} z_1 &= r_1 + r_4 \\ z_2 &= (r_2 + r_4) e^{i\varphi_{12}} \\ z_3 &= (r_3 + r_4) e^{-i\varphi_{31}} \quad \text{mit} \quad \varphi_{12} := \angle z_1 z_2, \quad \varphi_{31} := \angle z_3 z_4 z_1 \\ z_4 &= 0 \end{aligned}$$

ist.

$$\begin{aligned} 2 \left(\frac{z_1^2}{r_1^2} + \frac{z_2^2}{r_2^2} + \frac{z_3^2}{r_3^2} + \frac{z_4^2}{r_4^2} \right) &= \left(\frac{z_1}{r_1} + \frac{z_2}{r_2} + \frac{z_3}{r_3} + \frac{z_4}{r_4} \right)^2 \\ 2 \left(\frac{(r_1 + r_4)^2}{r_1^2} + \frac{(r_2 + r_4)^2 e^{i2\varphi_{12}}}{r_2^2} + \frac{(r_3 + r_4)^2 e^{-i2\varphi_{31}}}{r_3^2} \right) &= \left(\frac{r_1 + r_4}{r_1} + \frac{(r_2 + r_4) e^{i\varphi_{12}}}{r_2} + \frac{(r_3 + r_4) e^{-i\varphi_{31}}}{r_3} \right)^2 \\ 2 \left(\frac{1}{\frac{r_1^2}{(r_1 + r_4)^2}} + \frac{e^{i2\varphi_{12}}}{\frac{r_2^2}{(r_2 + r_4)^2}} + \frac{e^{-i2\varphi_{31}}}{\frac{r_3^2}{(r_3 + r_4)^2}} \right) &= \left(\frac{1}{\frac{r_1}{r_1 + r_4}} + \frac{e^{i\varphi_{12}}}{\frac{r_2}{r_2 + r_4}} + \frac{e^{-i\varphi_{31}}}{\frac{r_3}{r_3 + r_4}} \right)^2 \end{aligned}$$

$$\text{Mit } \alpha := \frac{1}{\frac{r_1}{r_1 + r_4}}, \quad \beta := \frac{1}{\frac{r_2}{r_2 + r_4}}, \quad \gamma := \frac{1}{\frac{r_3}{r_3 + r_4}}$$

folgt :

$$\begin{aligned} 2 \left(\frac{1}{\alpha^2} + \frac{e^{i2\varphi_{12}}}{\beta^2} + \frac{e^{-i2\varphi_{31}}}{\gamma^2} \right) &= \left(\frac{1}{\alpha} + \frac{e^{i\varphi_{12}}}{\beta} + \frac{e^{-i\varphi_{31}}}{\gamma} \right)^2 \\ 2 \left(\frac{1}{\alpha^2} + \frac{e^{i2\varphi_{12}}}{\beta^2} + \frac{e^{-i2\varphi_{31}}}{\gamma^2} \right) &= \frac{1}{\alpha^2} + \frac{e^{i2\varphi_{12}}}{\beta^2} + \frac{e^{-i2\varphi_{31}}}{\gamma^2} + 2 \left(\frac{e^{i\varphi_{12}}}{\alpha\beta} + \frac{e^{-i\varphi_{31}}}{\alpha\gamma} + \frac{e^{i(\varphi_{12} - \varphi_{31})}}{\beta\gamma} \right) \\ \frac{1}{\alpha^2} + \frac{e^{i2\varphi_{12}}}{\beta^2} + \frac{e^{-i2\varphi_{31}}}{\gamma^2} &= 2 \left(\frac{e^{i\varphi_{12}}}{\alpha\beta} + \frac{e^{-i\varphi_{31}}}{\alpha\gamma} + \frac{e^{i(\varphi_{12} - \varphi_{31})}}{\beta\gamma} \right) \\ \frac{1}{\alpha^2} + \frac{e^{i2\varphi_{12}}}{\beta^2} + \frac{e^{-i2\varphi_{31}}}{\gamma^2} - 2 \left(\frac{e^{i\varphi_{12}}}{\alpha\beta} + \frac{e^{-i\varphi_{31}}}{\alpha\gamma} + \frac{e^{i(\varphi_{12} - \varphi_{31})}}{\beta\gamma} \right) &= 0 \\ \underbrace{\hspace{15em}} &=: W \end{aligned}$$

$$W = \frac{1}{\alpha^2} + \frac{e^{i2\varphi_{12}}}{\beta^2} + \frac{e^{-i2\varphi_{31}}}{\gamma^2} - 2\left(\frac{e^{i\varphi_{12}}}{\alpha\beta} + \frac{e^{-i\varphi_{31}}}{\alpha\gamma} + \frac{e^{i(\varphi_{12}-\varphi_{31})}}{\beta\gamma}\right) \quad (7.1)$$

$$\operatorname{Re}(W) = \frac{1}{\alpha^2} + \frac{\cos 2\varphi_{12}}{\beta^2} + \frac{\cos 2\varphi_{31}}{\gamma^2} - 2\frac{\cos \varphi_{12}}{\alpha\beta} - 2\frac{\cos \varphi_{31}}{\alpha\gamma} - 2\frac{\cos(\varphi_{12}-\varphi_{31})}{\beta\gamma}$$

Additionstheorem :

$$\cos 2\varphi_{12} = \cos^2 \varphi_{12} - \sin^2 \varphi_{12}$$

$$\cos 2\varphi_{12} = \cos^2 \varphi_{12} - 1 + \cos^2 \varphi_{12}$$

$$\cos 2\varphi_{12} = 2\cos^2 \varphi_{12} - 1$$

Nach (1) , (2) , (3) sind

$$\cos \varphi_{12} = 1 - 2\frac{r_1 r_2}{(r_1+r_4)(r_2+r_4)} = 1-2\alpha\gamma$$

$$\cos \varphi_{23} = 1 - 2\frac{r_2 r_3}{(r_2+r_4)(r_3+r_4)} = 1-2\beta\gamma$$

$$\cos \varphi_{31} = 1 - 2\frac{r_3 r_1}{(r_3+r_4)(r_1+r_4)} = 1-2\alpha\gamma \quad ,$$

also

$$\underline{\cos \varphi_{12} = 1 - 2\alpha\beta} \quad ,$$

und

$$\cos 2\varphi_{12} = 2\cos^2 \varphi_{12} - 1$$

$$\underline{\cos 2\varphi_{12} = 2(1-2\alpha\beta)^2 - 1} \quad ,$$

und analog

$$\underline{\cos \varphi_{31} = 1 - 2\alpha\gamma}$$

$$\underline{\cos 2\varphi_{31} = 2(1-2\alpha\gamma)^2 - 1} \quad .$$

Additionstheorem und Symmetrieeigenschaften :

$$\cos(\varphi_{12}-\varphi_{31}) = \cos \varphi_{12} \cos \varphi_{31} + \sin \varphi_{12} \sin \varphi_{31}$$

$$\cos \varphi_{23} = \cos(2\pi - (\varphi_{12} + \varphi_{31}))$$

$$\cos \varphi_{23} = \cos(\varphi_{12} + \varphi_{31})$$

$$\cos \varphi_{23} = \cos \varphi_{12} \cos \varphi_{31} - \sin \varphi_{12} \sin \varphi_{31}$$

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$$\cos(\varphi_{12}-\varphi_{31}) + \cos \varphi_{23} = 2\cos \varphi_{12} \cos \varphi_{31}$$

$$\cos(\varphi_{12}-\varphi_{31}) = 2\cos \varphi_{12} \cos \varphi_{31} - \cos \varphi_{23}$$

$$\underline{\cos(\varphi_{12}-\varphi_{31}) = 2(1-2\alpha\beta)(1-2\alpha\gamma) - (1-2\beta\gamma)}$$

$$\begin{aligned} \operatorname{Re}(W) &= \frac{1}{\alpha^2} + \frac{\cos 2\varphi_{12}}{\beta^2} + \frac{\cos 2\varphi_{31}}{y^2} - 2\frac{\cos \varphi_{12}}{\alpha\beta} - 2\frac{\cos \varphi_{31}}{\alpha y} - 2\frac{\cos(\varphi_{12}-\varphi_{31})}{\beta y} \\ \operatorname{Re}(W) &= \frac{1}{\alpha^2} + \frac{(2(1-2\alpha\beta)^2 - 1)}{\beta^2} + \frac{(2(1-2\alpha y)^2 - 1)}{y^2} \\ &\quad - 2\frac{1-2\alpha\beta}{\alpha\beta} - 2\frac{1-2\alpha y}{\alpha y} - 2\frac{2(1-2\alpha\beta)(1-2\alpha y) - (1-2\beta y)}{\beta y} \\ \operatorname{Re}(W) &= \frac{1}{\alpha^2} + \frac{1-\alpha\beta+8\alpha^2\beta^2}{\beta^2} + \frac{1-8\alpha y+8\alpha^2 y^2}{y^2} \\ &\quad - 2\frac{1-2\alpha\beta}{\alpha\beta} - 2\frac{1-2\alpha y}{\alpha y} - 2\frac{2(1-2\alpha\beta)(1-2\alpha y) - (1-2\beta y)}{\beta y} \\ \operatorname{Re}(W) &= \frac{1}{\alpha^2} + \frac{1}{\beta^2} - \frac{8\alpha}{\beta} + 8\alpha^2 + \frac{1}{y^2} - \frac{8\alpha}{y} + 8\alpha^2 \\ &\quad - 2\frac{1-2\alpha\beta}{\alpha\beta} - 2\frac{1-2\alpha y}{\alpha y} - 2\frac{2(1-2\alpha\beta)(1-2\alpha y) - (1-2\beta y)}{\beta y} \\ \operatorname{Re}(W) &= \frac{1}{\alpha^2} + \frac{1}{\beta^2} - \frac{8\alpha}{\beta} + 8\alpha^2 + \frac{1}{y^2} - \frac{8\alpha}{y} + 8\alpha^2 \\ &\quad - \frac{2}{\alpha\beta} + 4 - \frac{2}{\alpha y} + 4 - 2\frac{2(1-2\alpha\beta)(1-2\alpha y) - (1-2\beta y)}{\beta y} \\ \operatorname{Re}(W) &= \frac{1}{\alpha^2} + \frac{1}{\beta^2} - \frac{8\alpha}{\beta} + 8\alpha^2 + \frac{1}{y^2} - \frac{8\alpha}{y} + 8\alpha^2 \\ &\quad - \frac{2}{\alpha\beta} + 4 - \frac{2}{\alpha y} + 4 - 2\frac{2(1-2\alpha\beta-2\alpha y+4\alpha^2\beta y) - 1 + 2\beta y}{\beta y} \\ \operatorname{Re}(W) &= \frac{1}{\alpha^2} + \frac{1}{\beta^2} - \frac{8\alpha}{\beta} + 8\alpha^2 + \frac{1}{y^2} - \frac{8\alpha}{y} + 8\alpha^2 \\ &\quad - \frac{2}{\alpha\beta} + 4 - \frac{2}{\alpha y} + 4 - \frac{4(1-2\alpha\beta-2\alpha y+4\alpha^2\beta y) - 2 + 4\beta y}{\beta y} \\ \operatorname{Re}(W) &= \frac{1}{\alpha^2} + \frac{1}{\beta^2} - \frac{8\alpha}{\beta} + 8\alpha^2 + \frac{1}{y^2} - \frac{8\alpha}{y} + 8\alpha^2 \\ &\quad - \frac{2}{\alpha\beta} + 4 - \frac{2}{\alpha y} + 4 - \frac{4-8\alpha\beta-8\alpha y+16\alpha^2\beta y - 2 + 4\beta y}{\beta y} \\ \operatorname{Re}(W) &= \frac{1}{\alpha^2} + \frac{1}{\beta^2} - \frac{8\alpha}{\beta} + 8\alpha^2 + \frac{1}{y^2} - \frac{8\alpha}{y} + 8\alpha^2 \\ &\quad - \frac{2}{\alpha\beta} + 4 - \frac{2}{\alpha y} + 4 - \frac{2-8\alpha\beta-8\alpha y+16\alpha^2\beta y+4\beta y}{\beta y} \\ \operatorname{Re}(W) &= \frac{1}{\alpha^2} + \frac{1}{\beta^2} - \frac{8\alpha}{\beta} + 8\alpha^2 + \frac{1}{y^2} - \frac{8\alpha}{y} + 8\alpha^2 \\ &\quad - \frac{2}{\alpha\beta} + 4 - \frac{2}{\alpha y} + 4 - \frac{2}{\beta y} + \frac{8\alpha}{y} + \frac{8\alpha}{\beta} - 16\alpha^2 - 4 \\ \operatorname{Re}(W) &= \frac{1}{\alpha^2} + \frac{1}{\beta^2} + \frac{1}{y^2} \\ &\quad - \frac{2}{\alpha\beta} + 4 - \frac{2}{\alpha y} - \frac{2}{\beta y} \\ \operatorname{Re}(W) &= \frac{1}{\alpha^2} + \frac{1}{\beta^2} + \frac{1}{y^2} - \frac{2}{\alpha\beta} - \frac{2}{\alpha y} - \frac{2}{\beta y} + 4 \end{aligned}$$

$$\operatorname{Re}(W) = \frac{1}{\alpha^2} + \frac{1}{\beta^2} + \frac{1}{\gamma^2} - 2\left(\frac{1}{\alpha\beta} + \frac{1}{\alpha\gamma} + \frac{1}{\beta\gamma}\right) + 4$$

$$\operatorname{Re}(W) = 2\left(\frac{1}{\alpha^2} + \frac{1}{\beta^2} + \frac{1}{\gamma^2}\right) - \left(\frac{1}{\alpha^2} + \frac{1}{\beta^2} + \frac{1}{\gamma^2} + 2\left(\frac{1}{\alpha\beta} + \frac{1}{\alpha\gamma} + \frac{1}{\beta\gamma}\right)\right) + 4$$

$$\operatorname{Re}(W) = 2\left(\frac{1}{\alpha^2} + \frac{1}{\beta^2} + \frac{1}{\gamma^2}\right) - \left(\frac{1}{\alpha} + \frac{1}{\beta} + \frac{1}{\gamma}\right)^2 + 4$$

Die Resubstitution

$$\alpha := \frac{1}{\frac{r_1}{r_1+r_4}} \quad \beta := \frac{1}{\frac{r_2}{r_2+r_4}} \quad \gamma := \frac{1}{\frac{r_3}{r_3+r_4}}$$

ergibt

$$\operatorname{Re}(V) = 2\left(\frac{1}{\left(\frac{r_1}{r_1+r_4}\right)^2} + \frac{1}{\left(\frac{r_2}{r_2+r_4}\right)^2} + \frac{1}{\left(\frac{r_3}{r_3+r_4}\right)^2}\right) - \left(\frac{1}{\left(\frac{r_1}{r_1+r_4}\right)} + \frac{1}{\left(\frac{r_2}{r_2+r_4}\right)} + \frac{1}{\left(\frac{r_3}{r_3+r_4}\right)}\right)^2 + 4 \quad .$$

Nach Gleichung (4) ist

$$2\left(\frac{1}{\left(\frac{r_1}{r_1+r_4}\right)^2} + \frac{1}{\left(\frac{r_2}{r_2+r_4}\right)^2} + \frac{1}{\left(\frac{r_3}{r_3+r_4}\right)^2}\right) - \left(\frac{1}{\left(\frac{r_1}{r_1+r_4}\right)} + \frac{1}{\left(\frac{r_2}{r_2+r_4}\right)} + \frac{1}{\left(\frac{r_3}{r_3+r_4}\right)}\right)^2 + 4 = 0 \quad ,$$

also

$$\operatorname{Re}(W) = 0 \quad .$$

Genau wie vorher, wird jetzt der Realteil von $\operatorname{Re}(We^{-i\varphi_{12}})$ betrachtet.

Man erhält eine zur Gleichung (7.1) zyklisch vertauschte Gleichung , entsprechend

$$\alpha, \beta, \gamma, \varphi_{12}, \varphi_{23}, \varphi_{31} \longrightarrow \beta, \gamma, \alpha, \varphi_{23}, \varphi_{31}, \varphi_{12} \quad .$$

Damit wird auch $\operatorname{Re}(We^{-i\varphi_{12}}) = 0$, und die Richtigkeit der Gleichung (7) ist gezeigt.

q.e.d.